

FPCUP USER WORKSHOP

ACTION „DOWNSTREAM SERVICE / APPLICATION
DEVELOPMENT FOR NATIONAL STATISTICS AND REPORTING”

Concept and Demonstration

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A satellite with two large solar panel arrays is shown in orbit above Earth. The satellite's body is gold-colored, and the solar panels are silver with a grid pattern. The Earth below shows green landmasses, blue oceans, and white clouds. The curvature of the planet and the blackness of space are visible in the background.

CONCEPTS AND LIVE DEMO

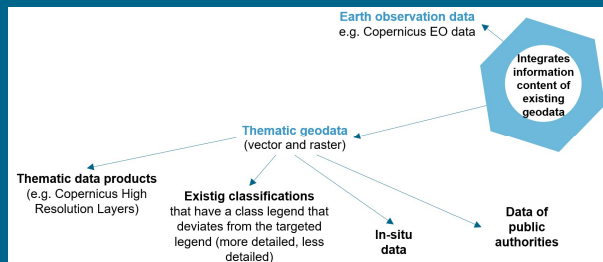
FPCUP Tool

Stage 1



Definition of broader class regions indicating potential locations of training areas

- Integration of existing geodata

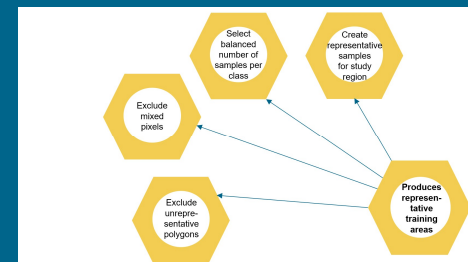


Stage 2



Selection of training areas (sampling)

- Produce representative training areas



Goals of Live Demo



Introduce concepts and examples for Jupyter Notebook workflows

- to create input data sets (stage 1)
- for selecting samples (stage 2)



Why Jupyter Notebooks and not any GIS

- no licenses, runs everywhere
- interactive and adaptable (like clicks on a GUI)
- can also be automated (impossible with GUI)
- documentation and code combined
- reproducible
- can be extended on demand

FPCUP Tool – Jupyter Notebooks



What

Interactive sampling tool to define a workflow for creating training data

How

- Jupyter notebooks
- Python libraries
- HTML Documentation
- Additional example Workflows

Finally write samples to a shape file. You can use it for the actual classification task.

```
In [26]: df_smp1s.to_file(fn_final, driver=driver_type, crs=df_clean.crs)
```

Bonus

Suppose you want to save circular polygons with a given diameter instead of points. In this case just run the cell below. It produces a circular polygons with the `diameter` specified below. It is prudent to keep the diameter smaller than the distance of the inward buffer defined Input 0/8 in order to avoid mixed pixels or overlapping regions.

Change diameter a filename according to your preferences.

```
In [27]: #diameter in m (if using UTM)
diameter = 10

#name of file to be created
fn_final_poly = os.path.join(indir, 'eco', 'ecofinalpoly.shp')

df_smp1s.buffer(diameter).to_file(fn_final_poly, driver=driver_type, crs=df_clean.crs)
```

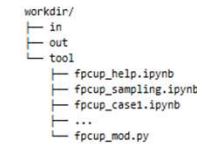
Done!

Jupyter Notebook

2b) Setup of fpcup tools

Copy the files `fpcup_mod.py` and corresponding notebooks (e.g. `fpcup_sampling.ipynb`, `fpcup_case1.ipynb`, `fpcup_help.ipynb`) to the same folder of your choice. Use the Jupyter web interface to access this folder and start using one of the notebooks. It is important to keep `fpcup_mod.py` in the same directory as your notebooks.

Below is a suggestion for a simple directory structure suitable for simple projects. Copy the notebooks and the python file to the tool directory. Use the Jupyter web interface (see section 2c) to access the "tool" folder and start using one of the notebooks.



Documentation

2c) Running Jupyter

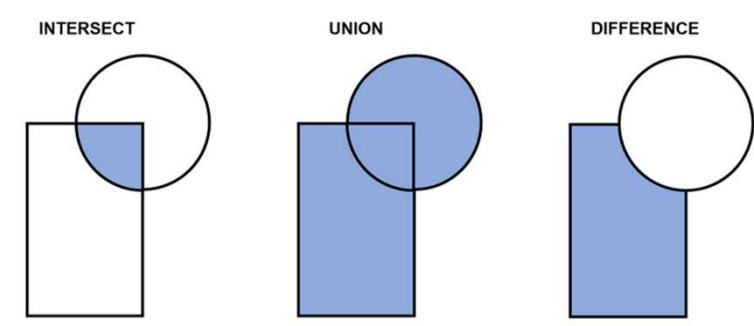
In order to access your notebooks, the Jupyter web interface needs to be started on the drive where your notebooks are located. Note that the location of your data is not affected by this limitation and can be located on any drive. If necessary switch the drive like this:

```
(fpcup) C:\> u:
Now you can run Jupyter Notebook located on U:
(fpcup) U:\> jupyter notebook
```

A window in your browser of choice should pop up. From now on, you can click and navigate using the web interface. Navigate to your folder where you copied the notebooks and start using one of them. As an example, demonstrating the functioning of the training area selection tool, you can open

2) Operations for vector combination

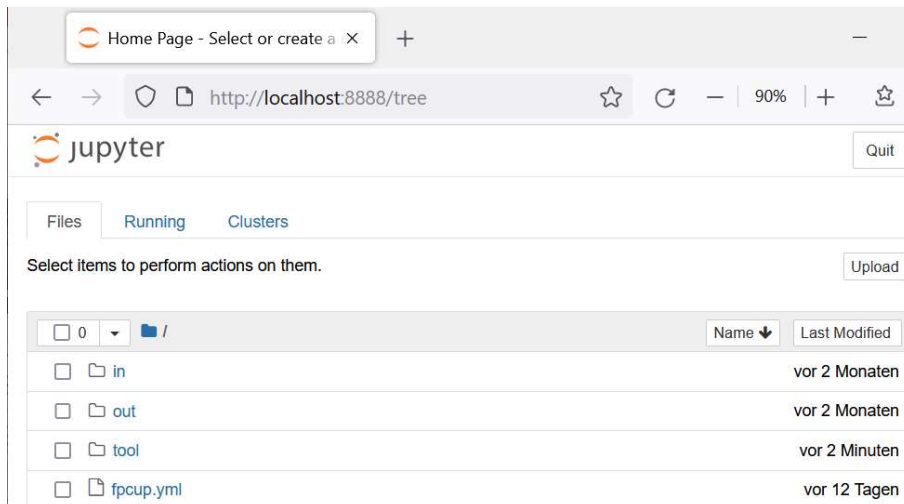
The three functions below provide the overlay operations shown in this image.



```
fcp.intersect(fn1, fn2, fnout):
Intersect two vector files and write result (blue area) to disk.

fn1: name of first input file
fn2: name of second input file
fnout: name of output file
```

FPCUP Tool – Jupyter Notebooks



Jupyter Start Page

2b) Setup of fpcup tools

Copy the files `fpcup_mod.py` and corresponding notebooks (e.g. `fpcup_sampling.ipynb`, `fpcup_case1.ipynb`, `fpcup_help.ipynb`) to the same folder of your choice. Use the Jupyter web interface to access this folder and start using one of the notebooks. It is important to keep `fpcup_mod.py` in the same directory as your notebooks.

Below is a suggestion for a simple directory structure suitable for simple projects. Copy the notebooks and the python file to the tool directory.

Use the Jupyter web interface (see section 2c) to access the "tool" folder and start using one of the notebooks.

```
workdir/  
├── in  
├── out  
└── tool  
    ├── fpcup_help.ipynb  
    ├── fpcup_sampling.ipynb  
    ├── fpcup_case1.ipynb  
    ├── ...  
    └── fpcup_mod.py
```

Documentation

2c) Running Jupyter

In order to access your notebooks, the Jupyter web interface needs to be started on the drive where your notebooks are located. Note that the location of your data is not affected by this limitation and can be located on any drive. If necessary switch the drive like this:

```
(fpcup) C:\> u:
```

Now you can run Jupyter Notebook located on U:

```
(fpcup) U:\> jupyter notebook
```

A window in your browser of choice should pop up. From now on, you can click and navigate using the web interface. Navigate to your folder where you copied the notebooks and start using one of them. As an example, demonstrating the functioning of the training area selection tool, you can open e.g. `fpcup_case1.ipynb`.

Later when you are finished, quit the notebook and deactivate the environment.

```
(fpcup) U:\> conda deactivate
```

FPCUP Tool



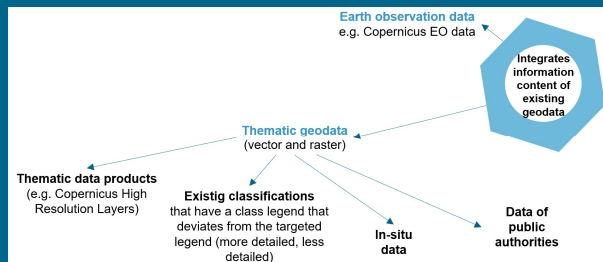
Stage 1

Stage 2

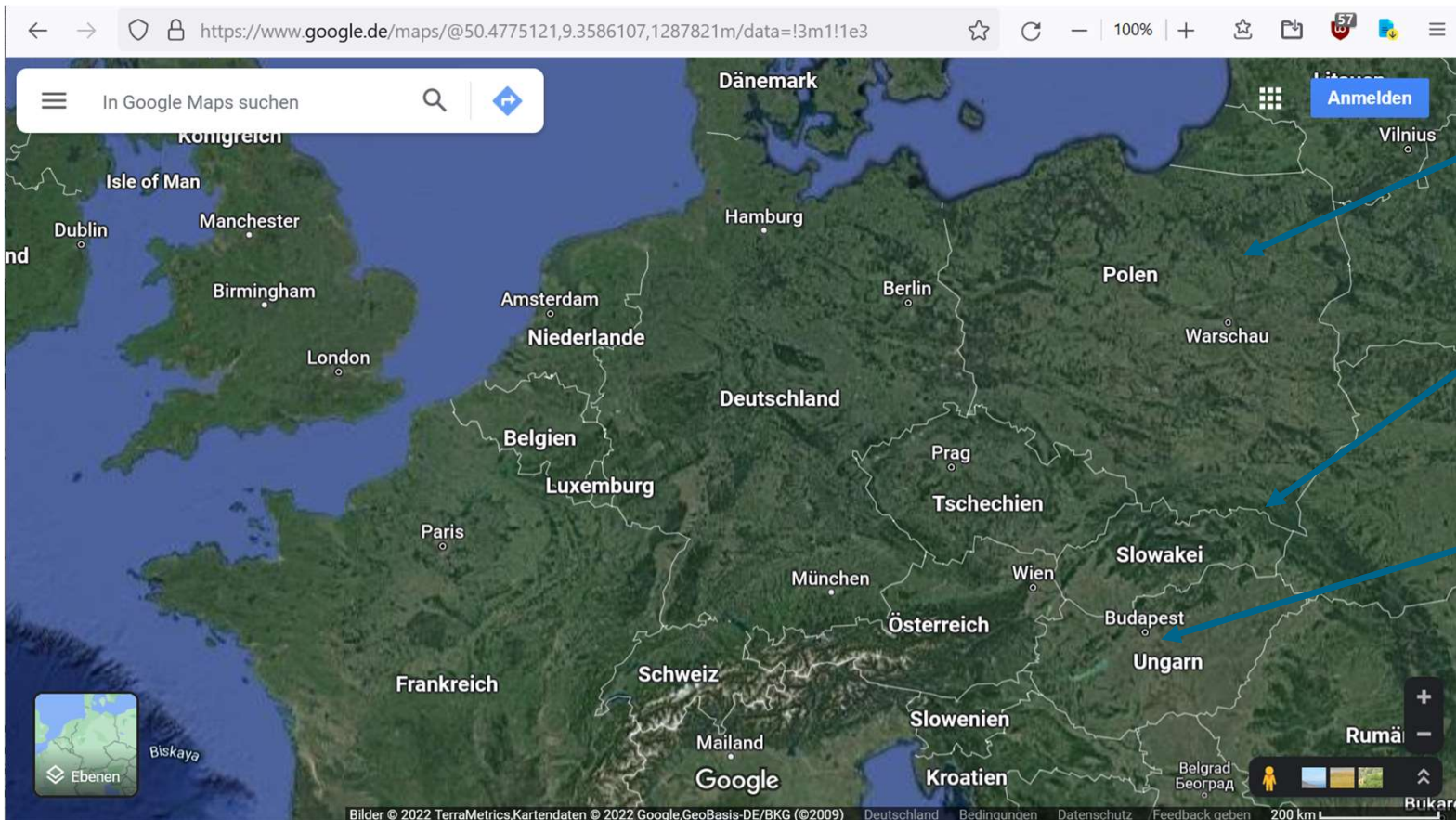


Definition of broader class regions indicating potential locations of training areas

➤ Integration of existing geodata



Data Types and Spatial Relationships



Satellite RGB
Raster

Country
Vector (Polygon)

City
Vector (Point)

- Target: Retrieve information using spatial relations from raster and vector files

Stage 1 Workflow Example: Define Broader Regions for Class “Flood Plains”



Criteria to be fulfilled:

- Low lying areas (200m - 400m)
- Slope lower than 3 degrees

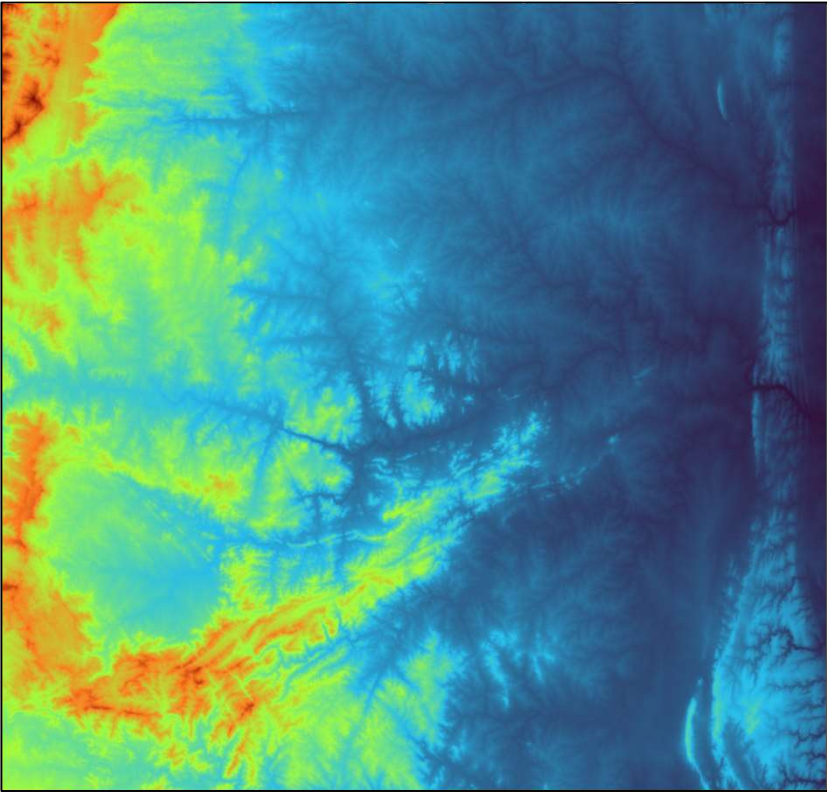
Workflow:

- Select polygons with pixels between 200m - 400m
- Select polygons with pixels lower than 3 degrees
- Intersect both polygons

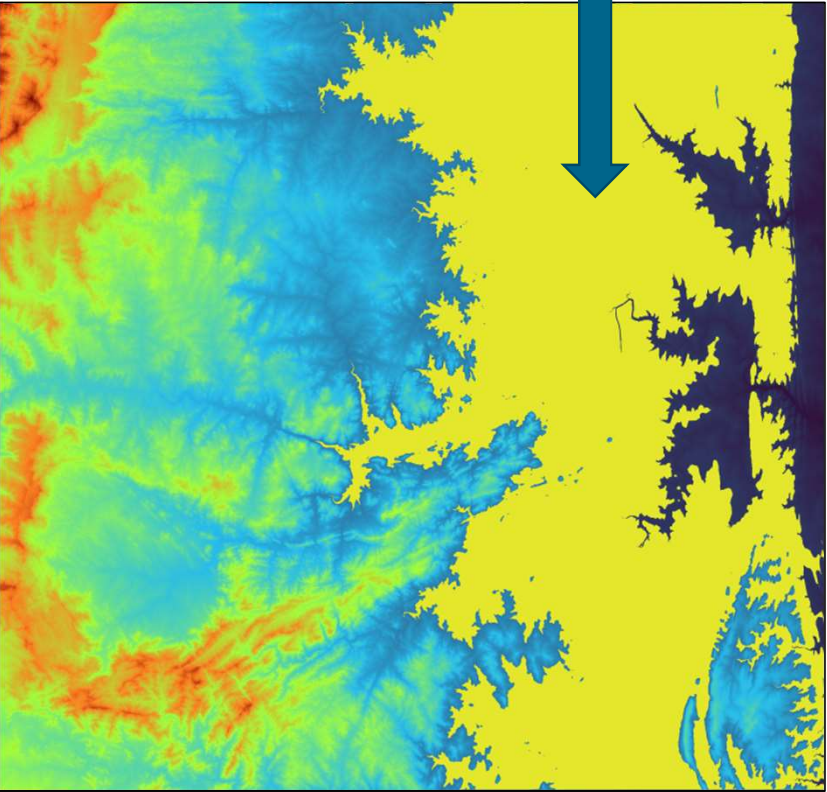
Stage 1 Workflow „Flood Plains“: Select low lying areas



DEM altitude



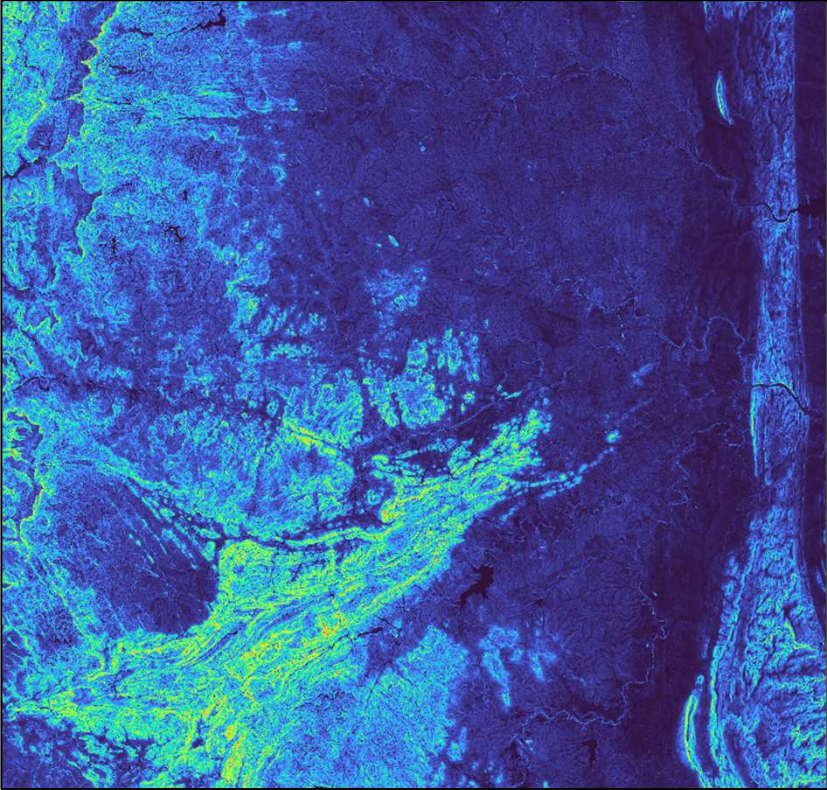
Low lying areas



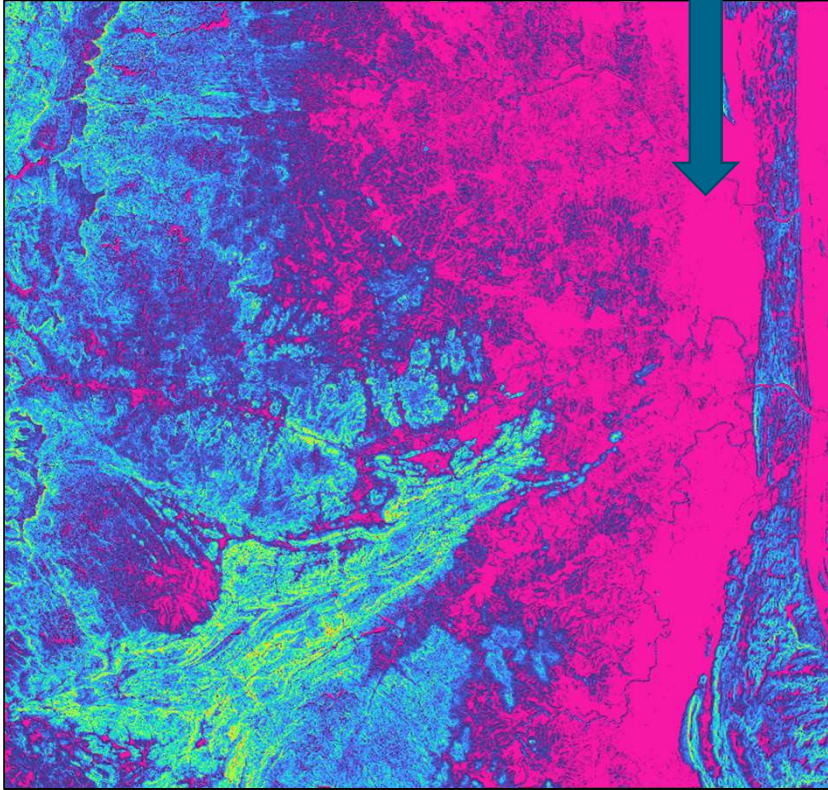
Stage 1 Workflow „Flood Plains“: Select flat areas



Slope



Flat areas

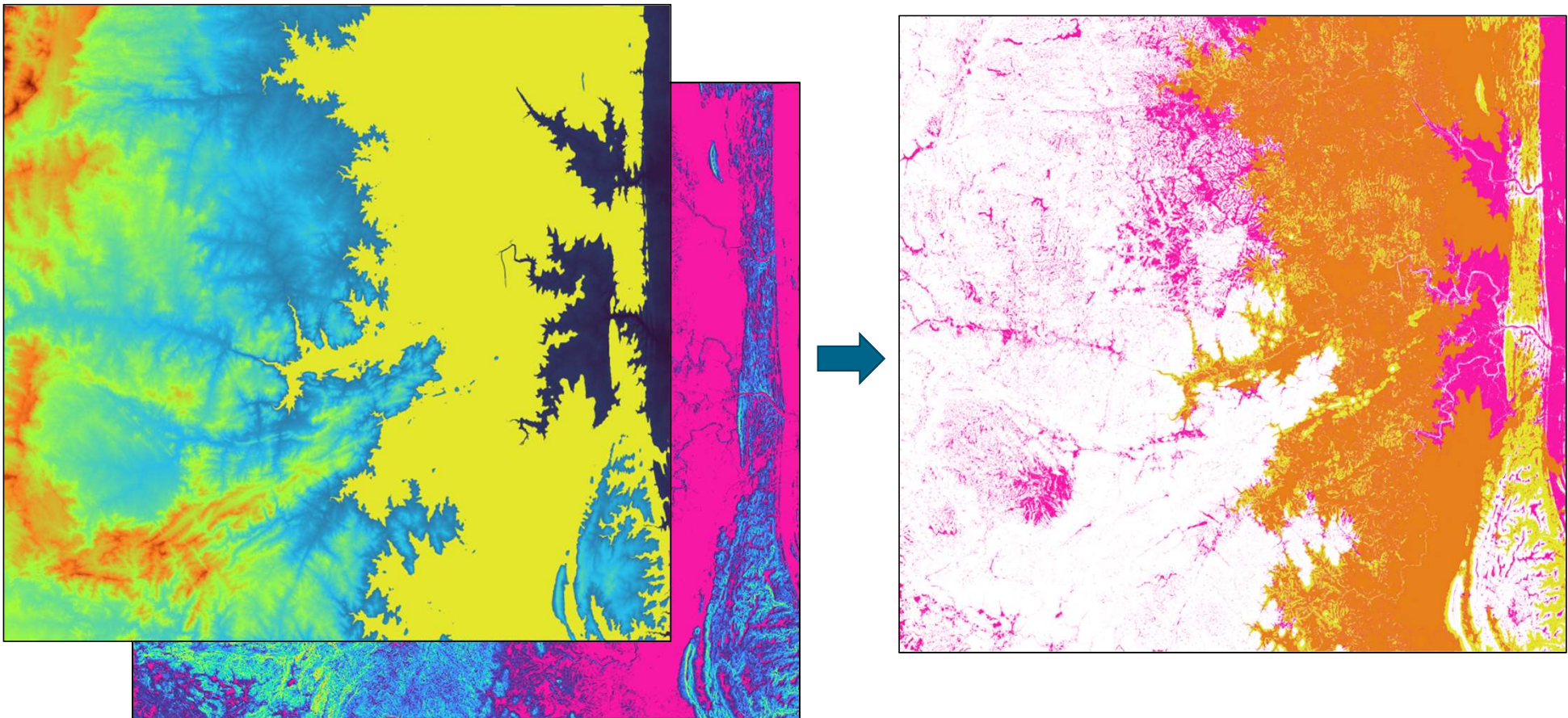


Stage 1 Workflow „Flood Plains“: Combine flat areas with relatively low lying areas



Combine

Intersection



Demonstration



Stage 1

- Case: Potential Flood Plains
- `fpcup_case_flood.ipynb`

Stage 1 Workflow Example: Define Broader Regions for Class “Riparian Forest”



Criteria to be fulfilled:

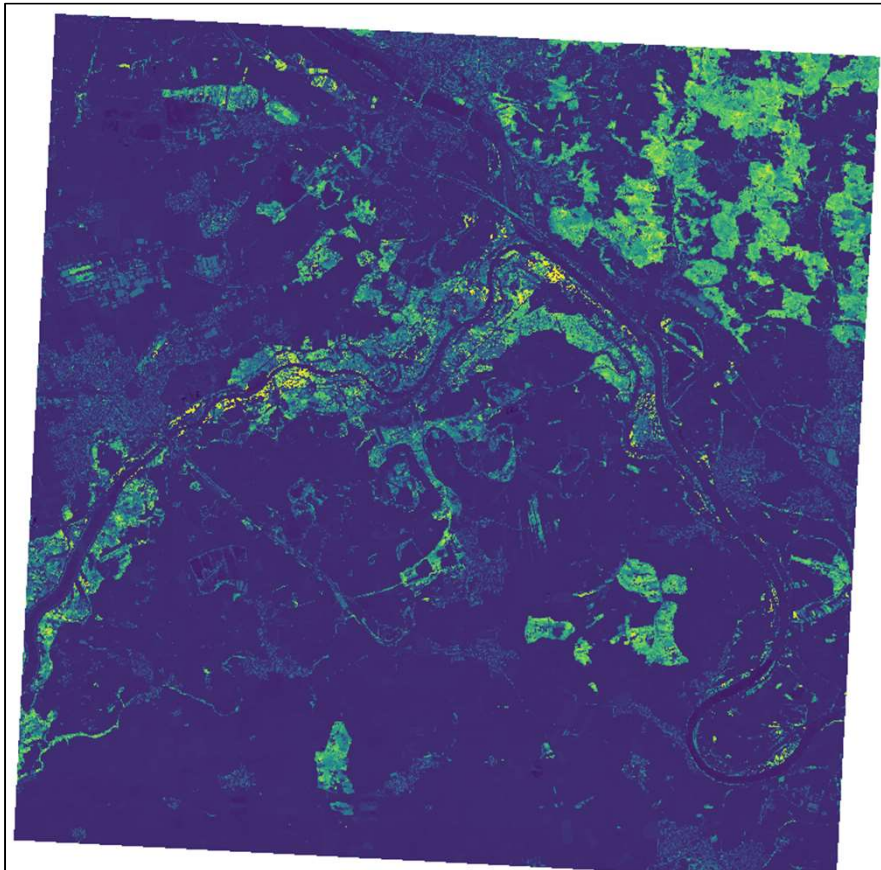
- Vegetation above 8m
- Polygons larger 100 m²
- In potential riparian zone

Workflow

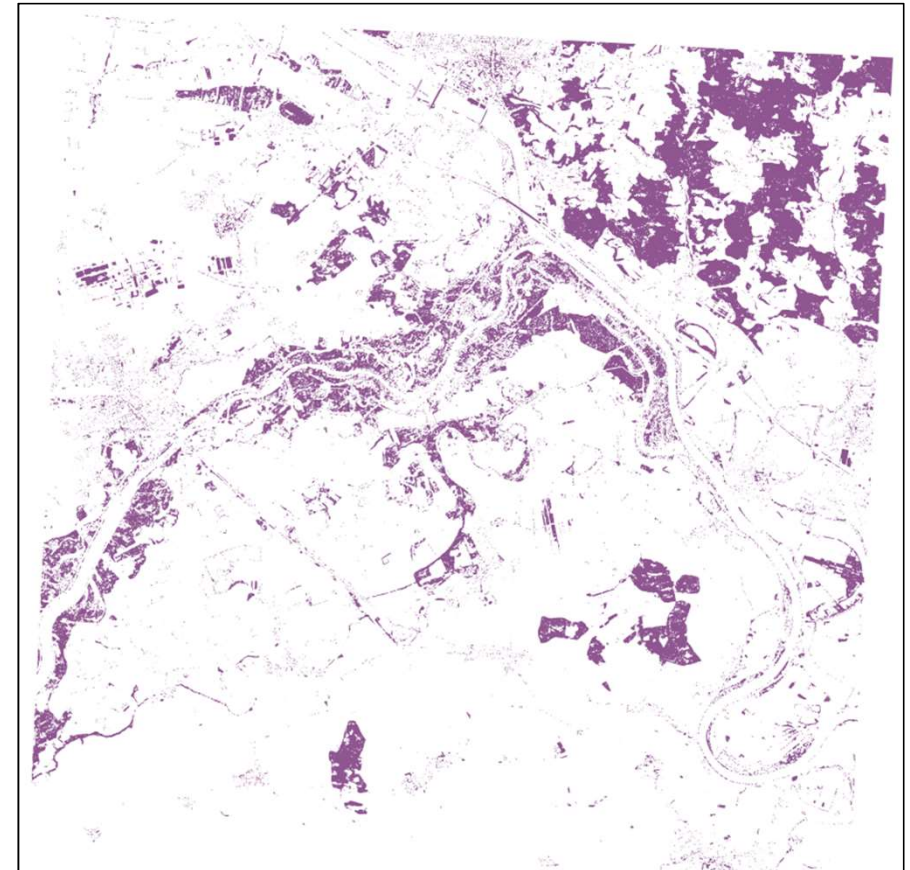
- Filter high structures
- Exclude small areas (mainly for speed-up)
- Intersect with riparian zones
- Exclude building footprints
- Exclude small areas (not shown, but theoretically necessary)

Workflow Riparian Forest: Height above Ground

Height above ground

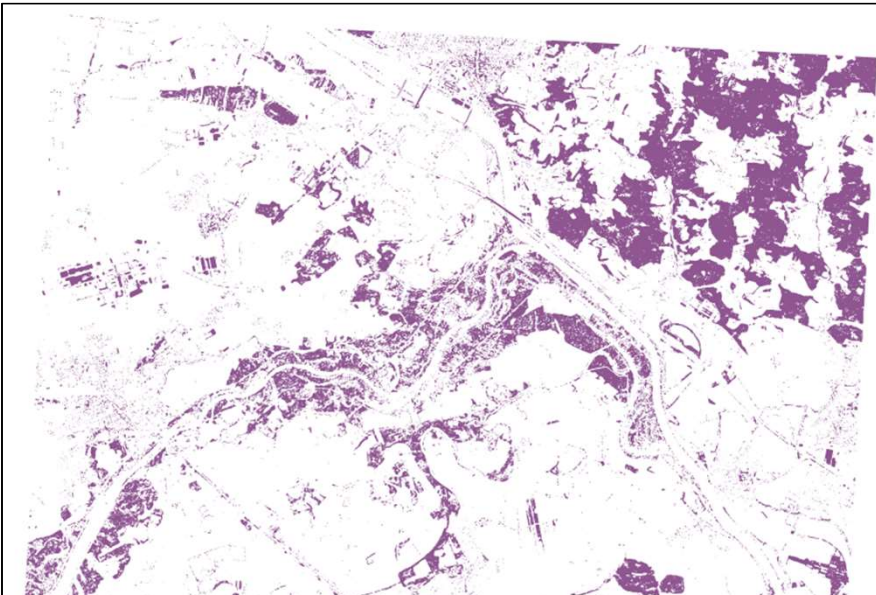


Height mask with structures > 8m

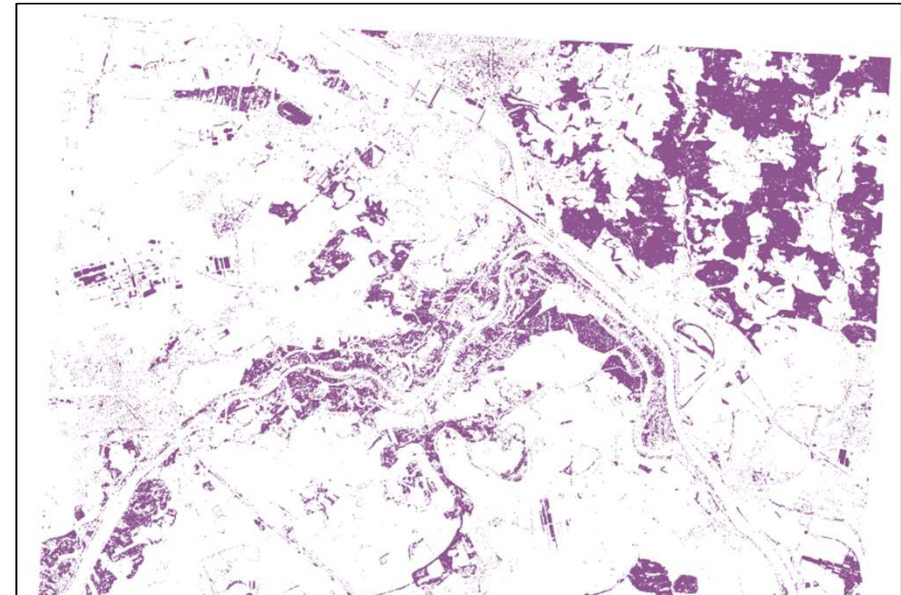


Workflow Riparian Forest: Remove Small Polygons

All Polygons



Polygons > 100 square meters



```
# perform calculation
```

```
fcf.filter_by_area(fn_height_mask, fn_height_mask_filtered, 100)
```

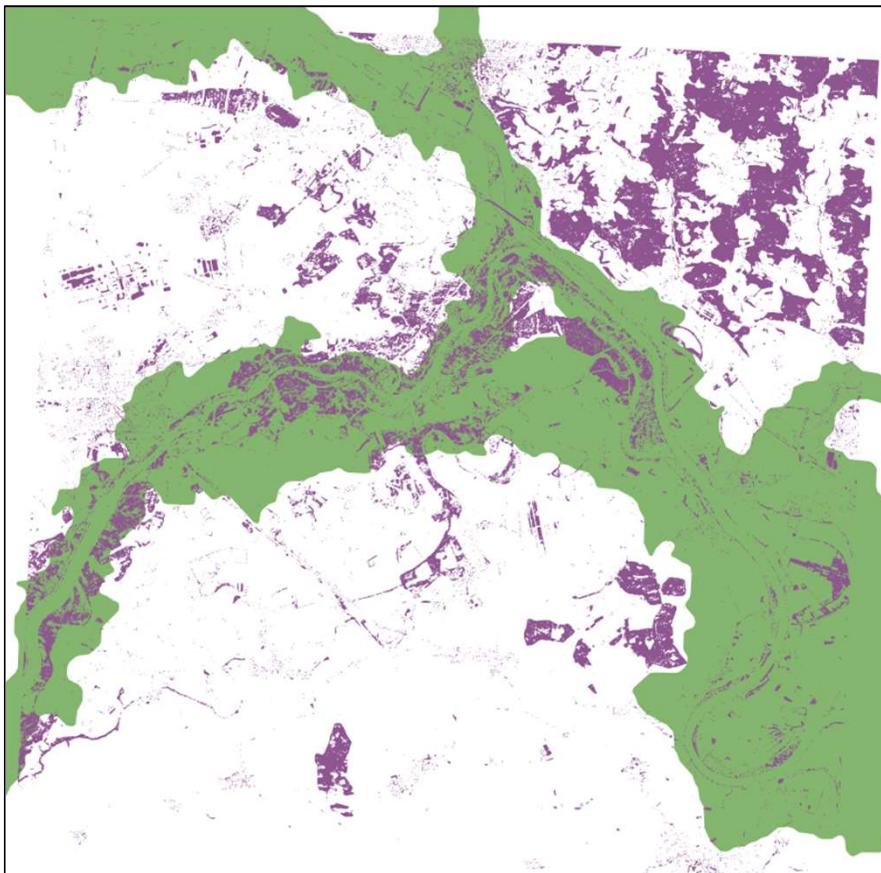
```
Coordinate system: epsg:25832
```

```
Properties before filter: number of elements: 31275, min area: 1.0, max area: 5731008.0
```

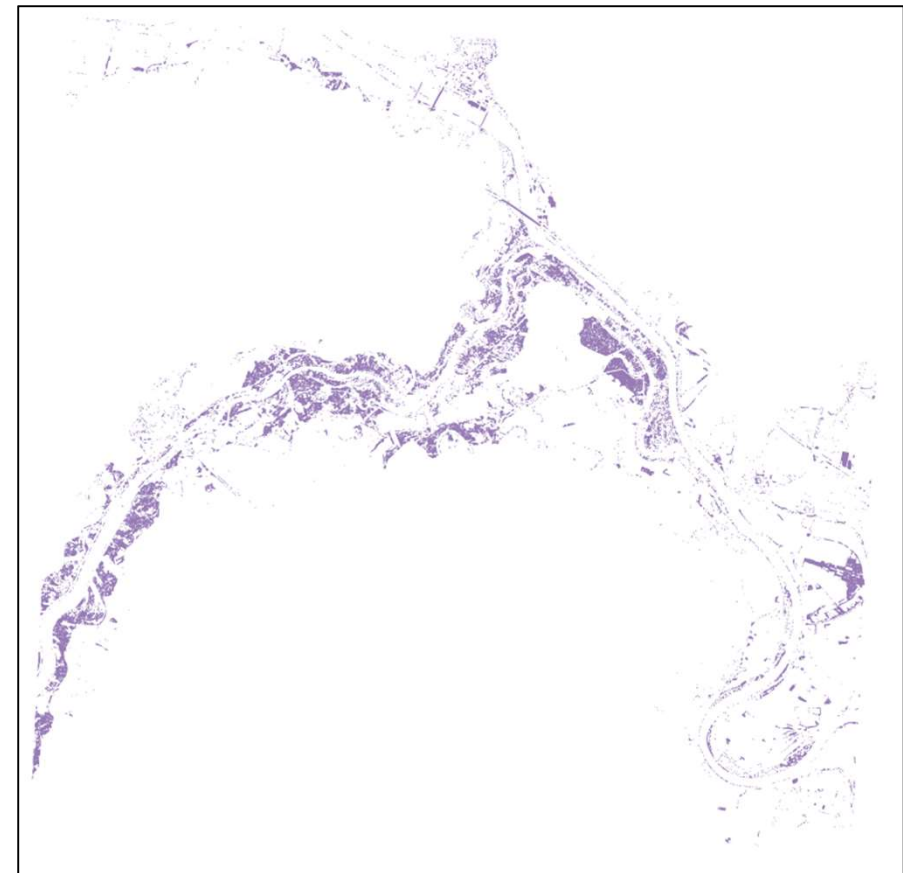
```
Properties after filter: number of elements: 10080, min area: 100.0, max area: 5731008.0
```


Workflow Riparian Forest: Height and Riparian Zones

Riparian zones and height mask



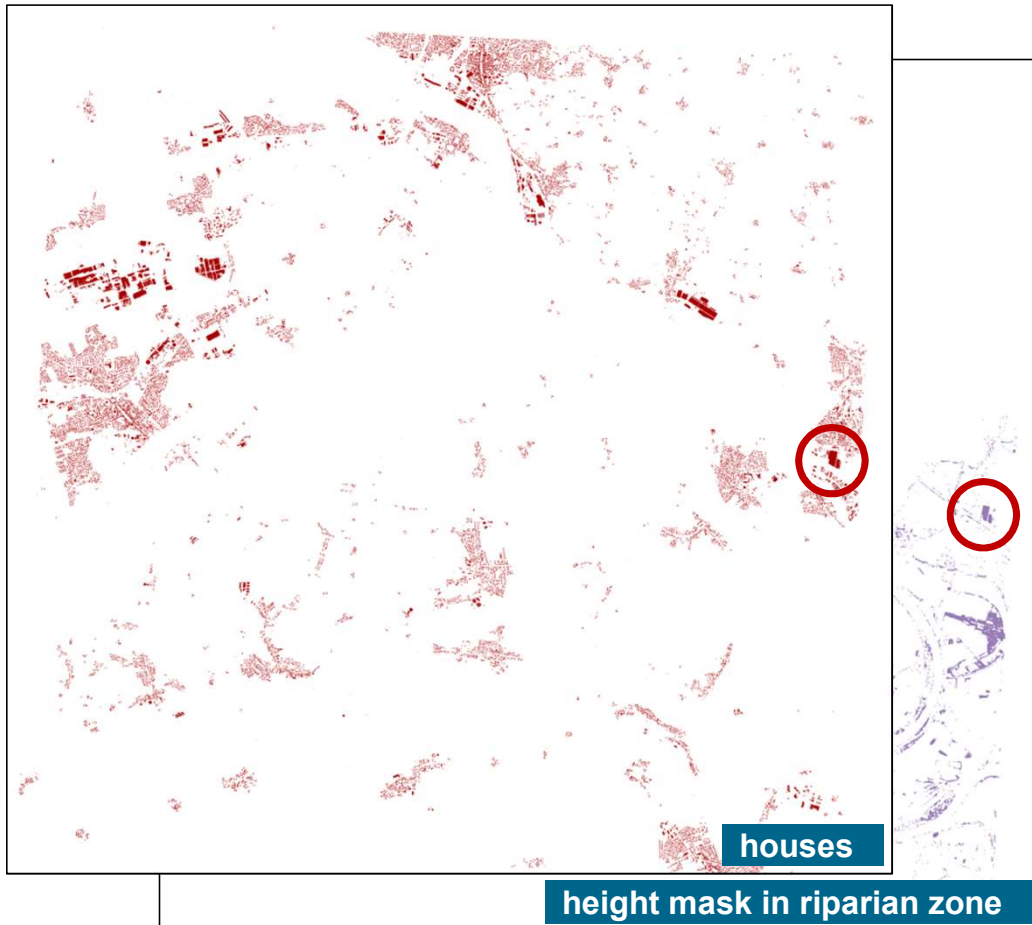
Height mask in riparian zones



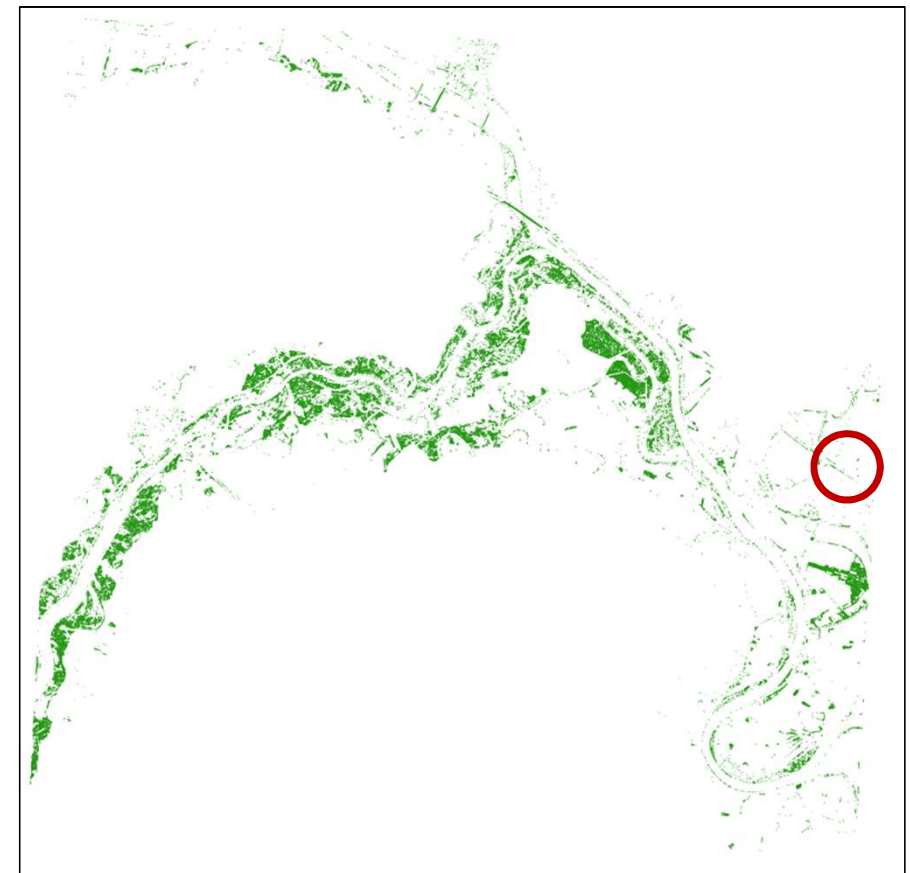
Workflow Riparian Forest: Height Mask Minus Houses



Remove houses from height mask



Riparian Forests



Demonstration



Stage 1

- Case: Riparian Forests
- `fpcup_case_ripa.ipynb`

Stage 2



Stage 1

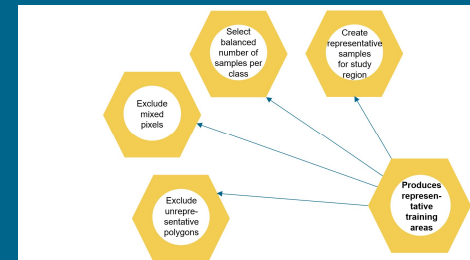


Stage 2

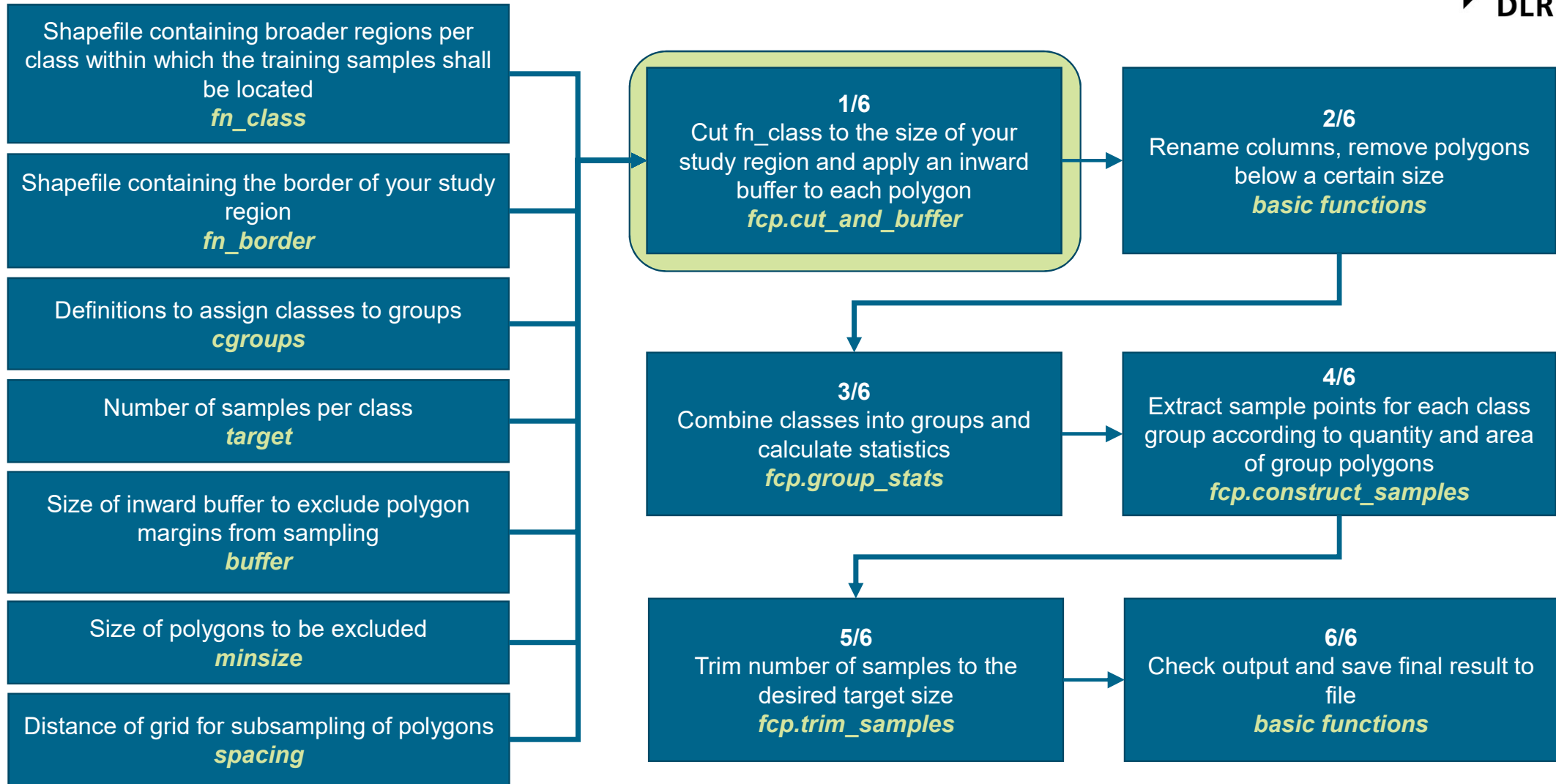


Selection of training areas (sampling)

- Produce representative training areas



Sampling Tool (Stage 2): General Workflow with Stage 1 Data



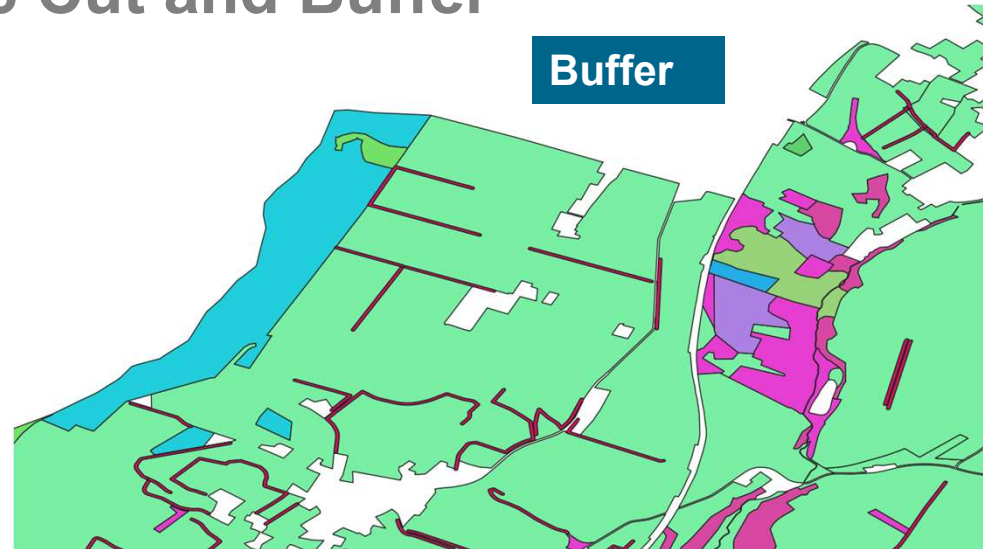
Sampling Visualization: 1/6 Cut and Buffer



Purpose

- Cut data to region of interest
- Exclude mixed pixels

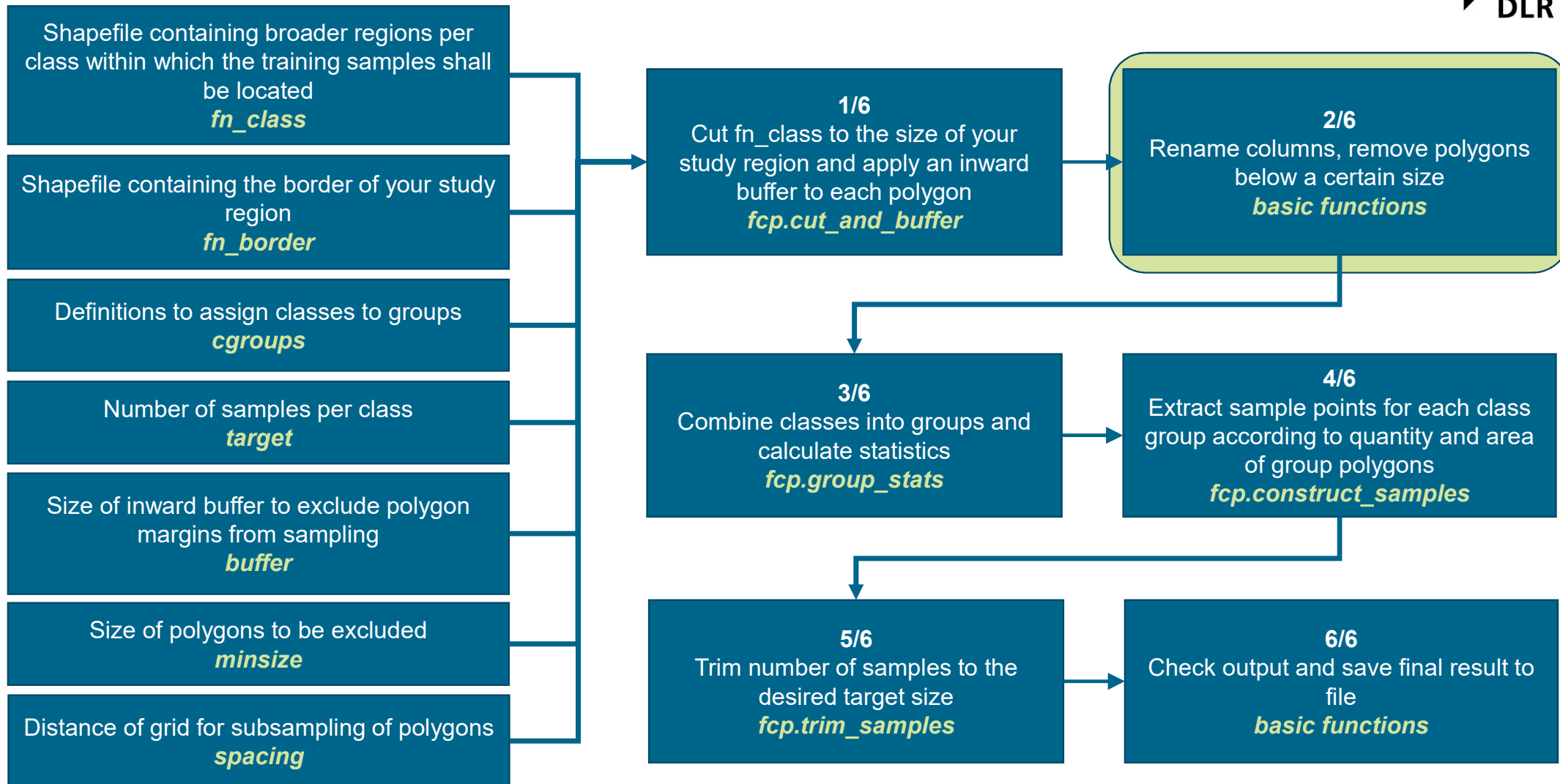
Buffer



Cut



Sampling Tool: General Workflow



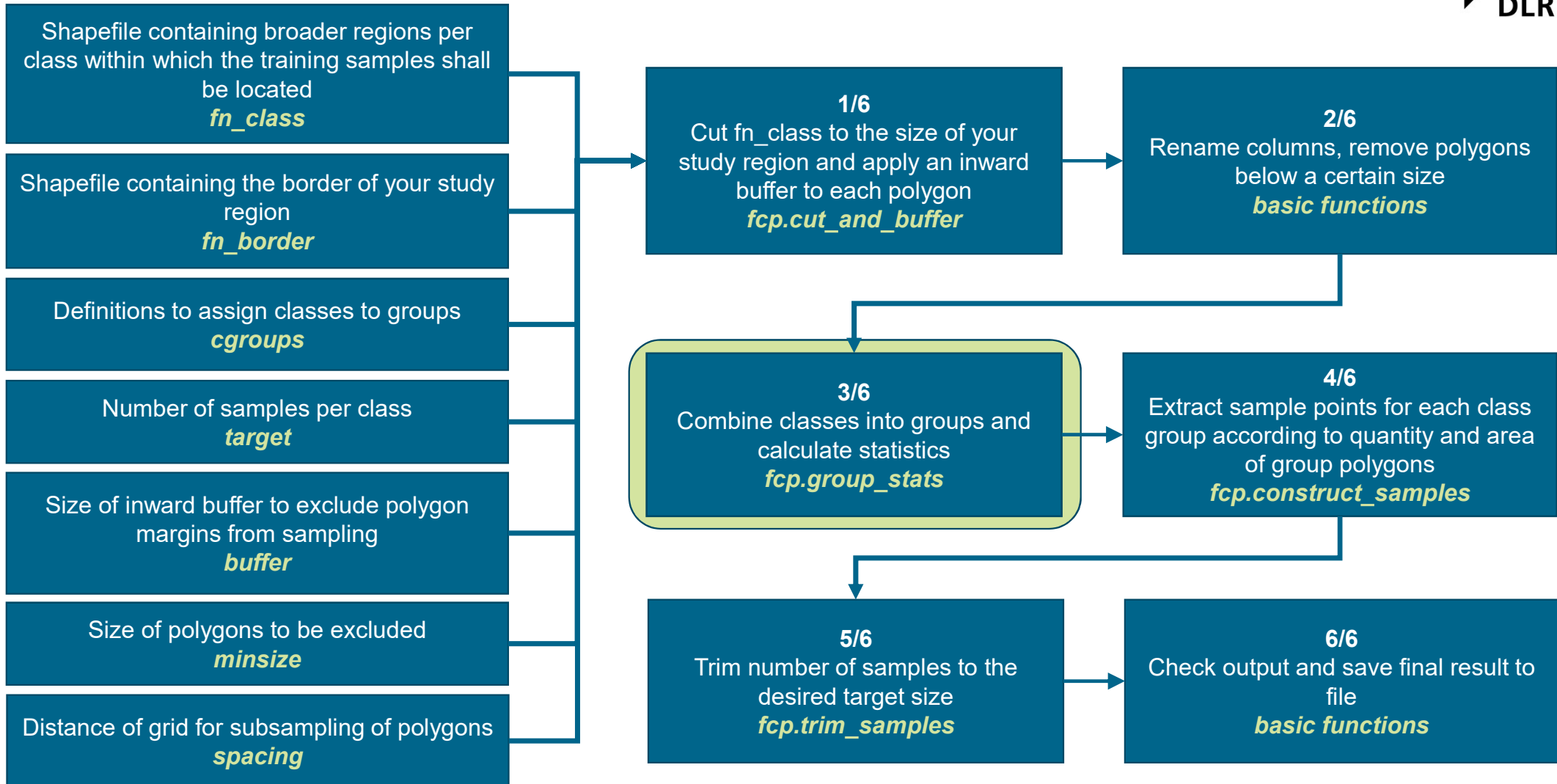
Sampling Visualization: Step 2/6) Rename and Clean-up



Purpose

- Internal renaming operations
- Exclude small areas

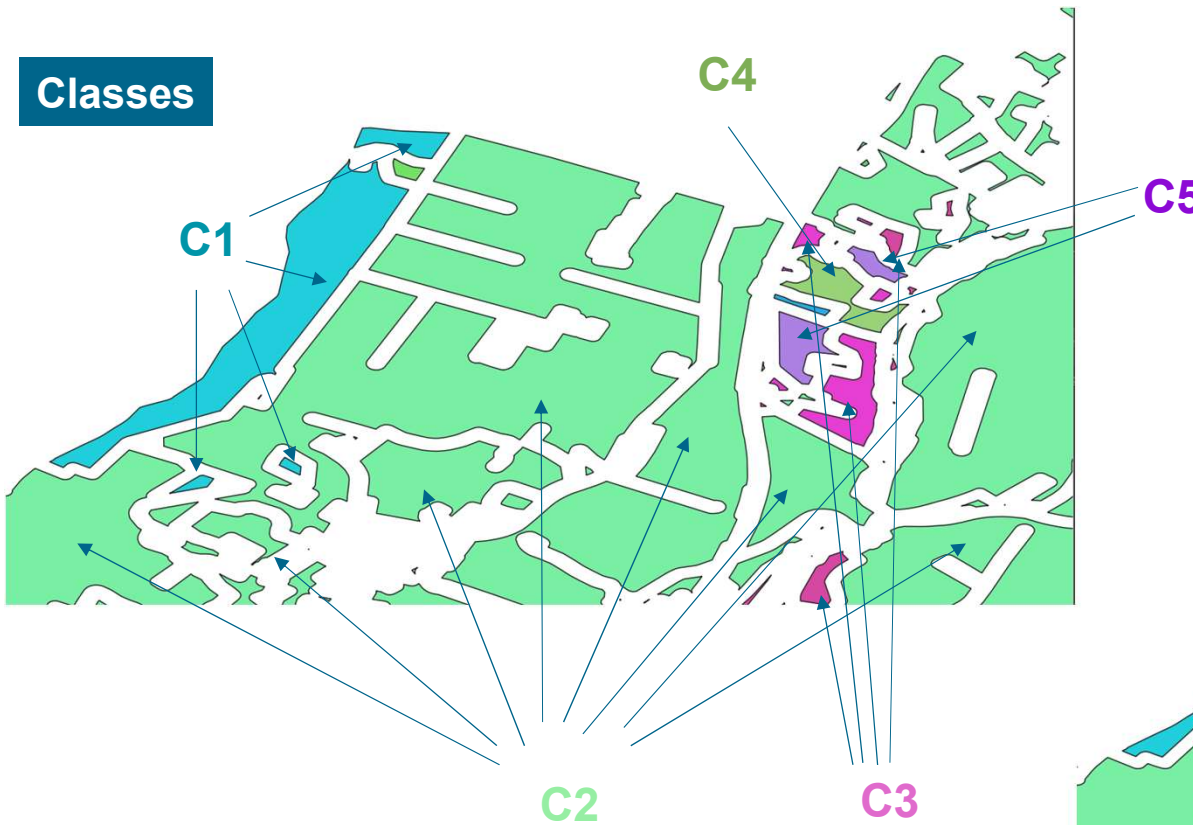
Sampling Tool: General Workflow



Sampling Visualization: 3/6) Assign classes to class groups, remove redundant classes, get stats



Classes



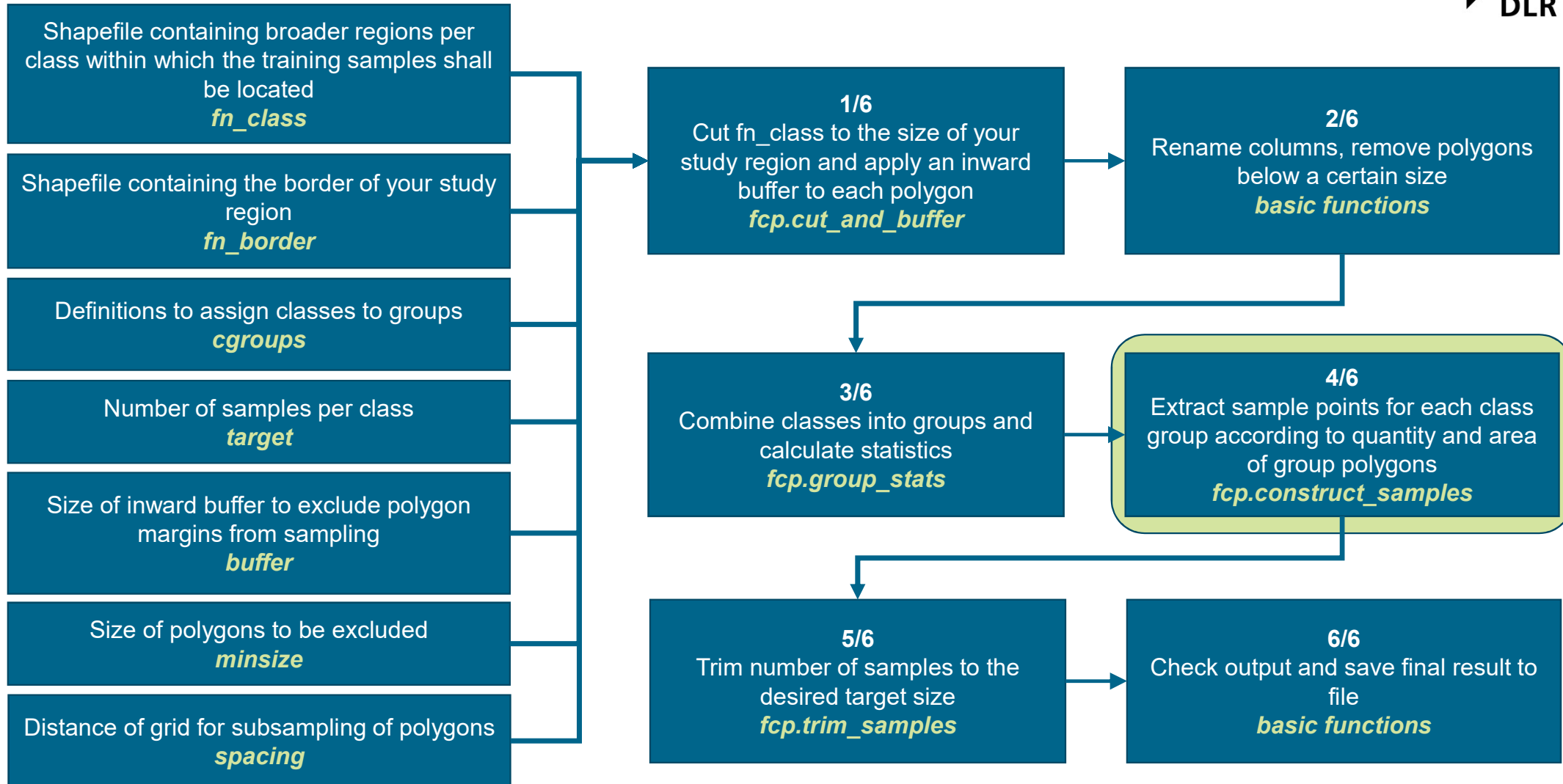
Notation:

```
{  
  G1 = ['C1'],  
  G2 = ['C2'],  
  G4 = ['C3', 'C4', 'C5']  
}
```

Groups



Step 4/6) Create sample point list for each of the groups - General Workflow

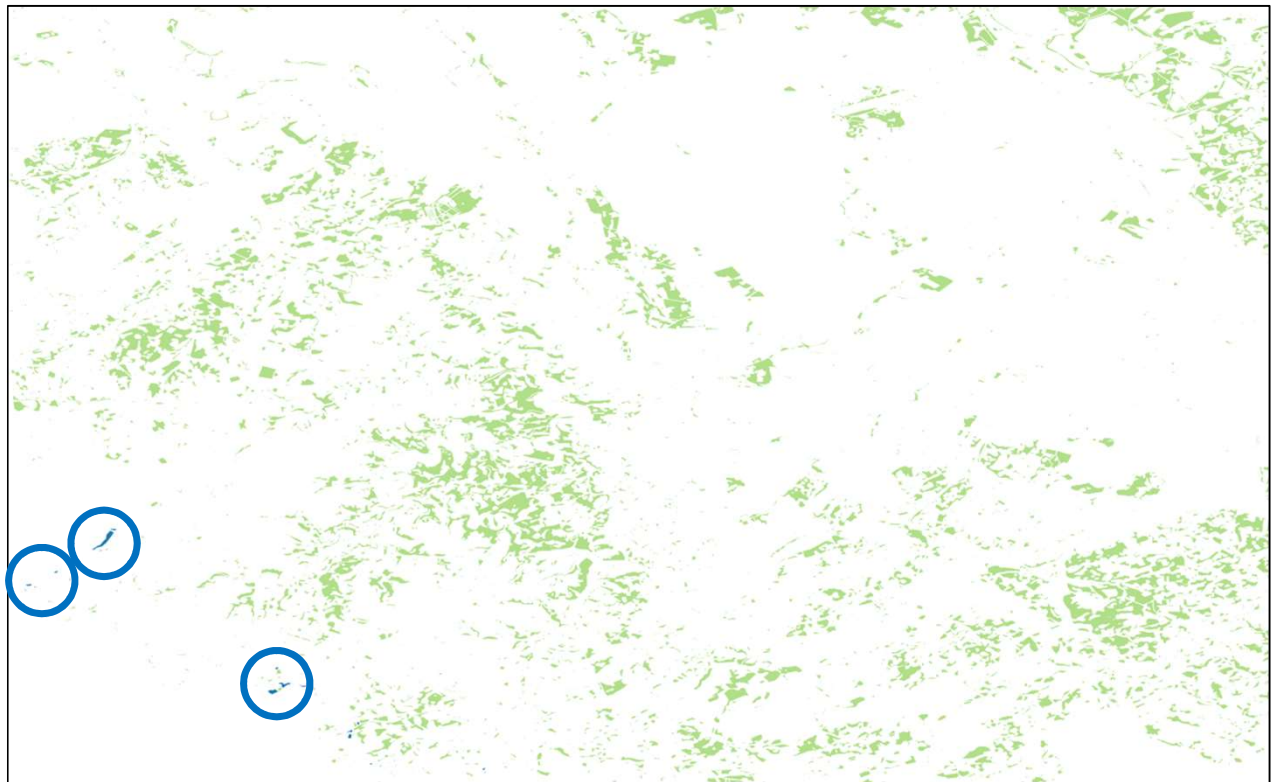


Step 4/6) Create sample point list for each of the groups

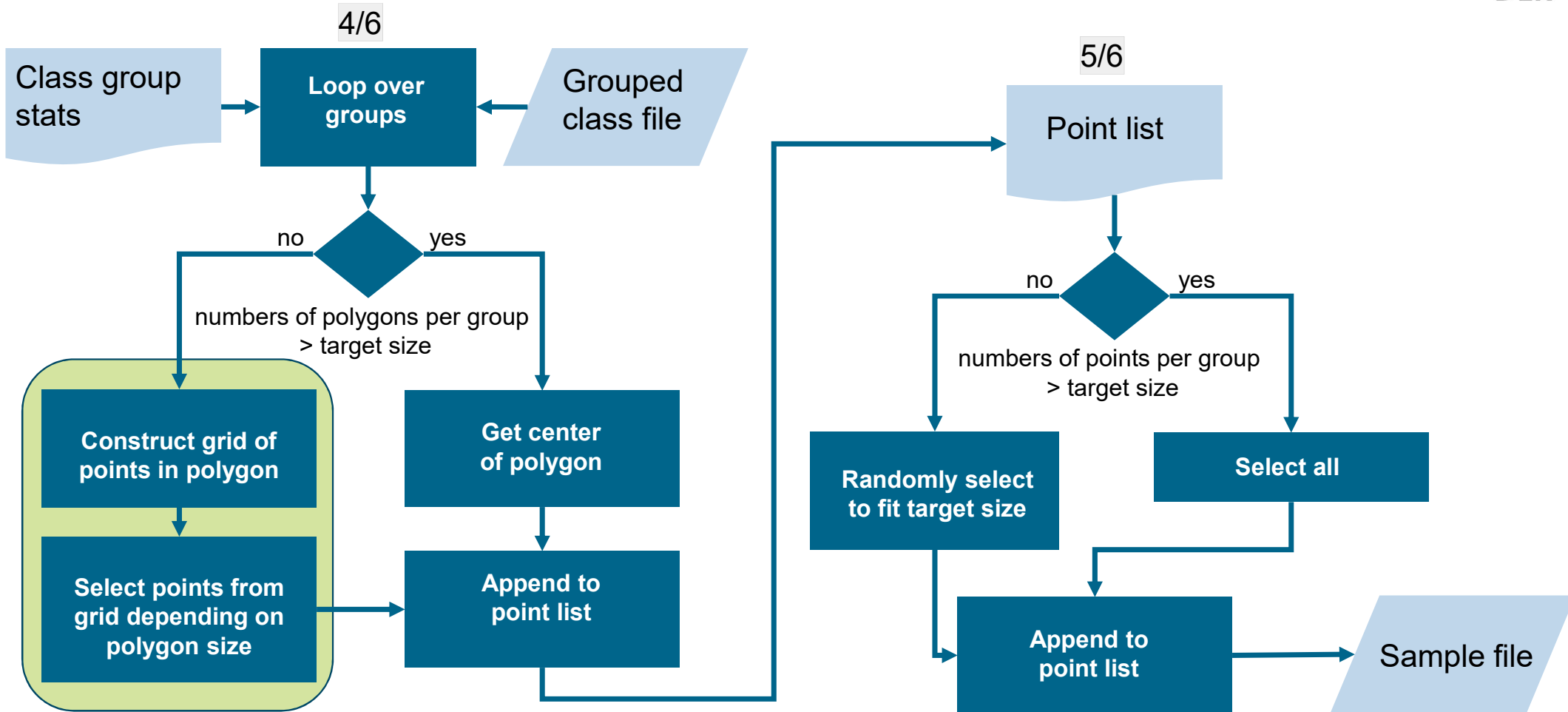


Two cases

- More polygons than required samples (green)
- Less polygons than required samples (blue)



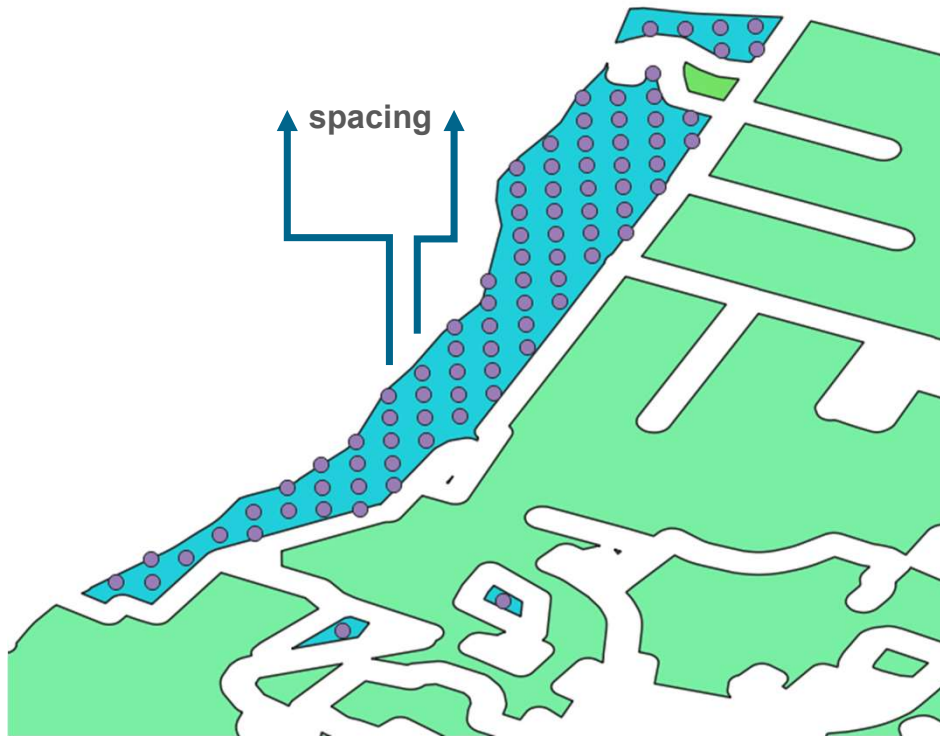
Workflow Detail: Sample Construction



Step 4/6) Sample Construction: Gridding



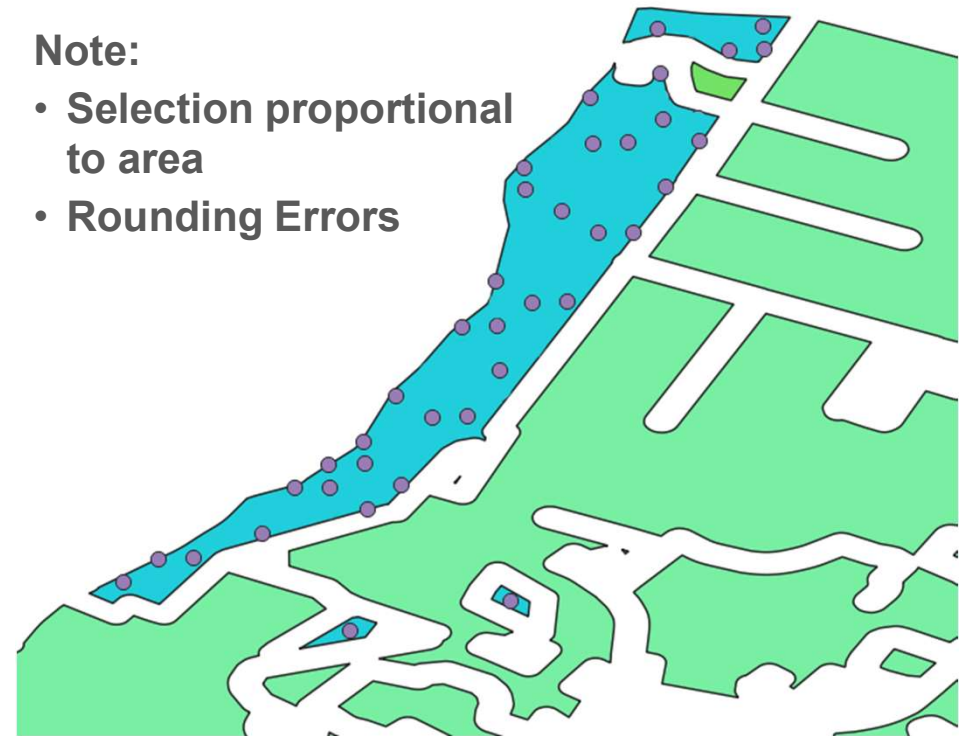
Gridding



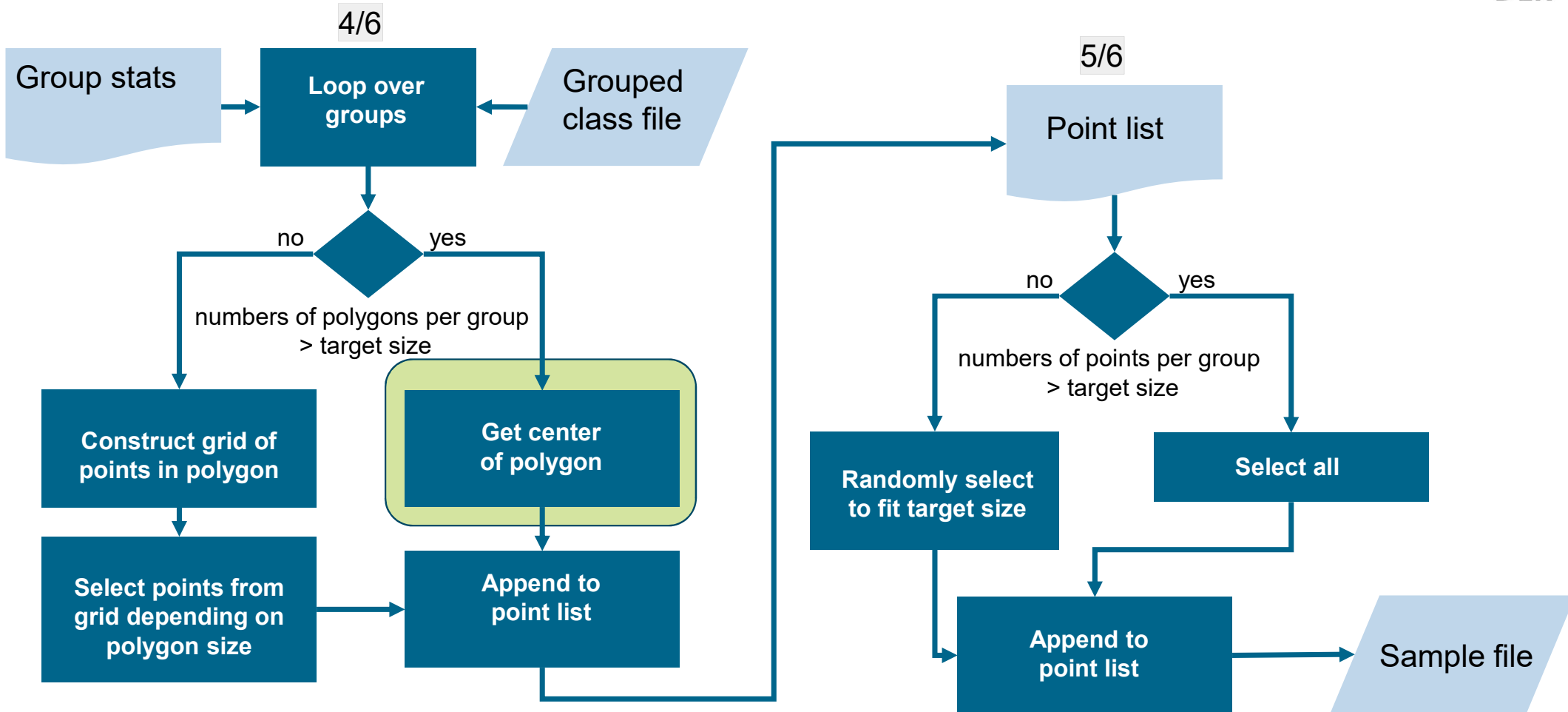
Select points from grid

Note:

- Selection proportional to area
- Rounding Errors



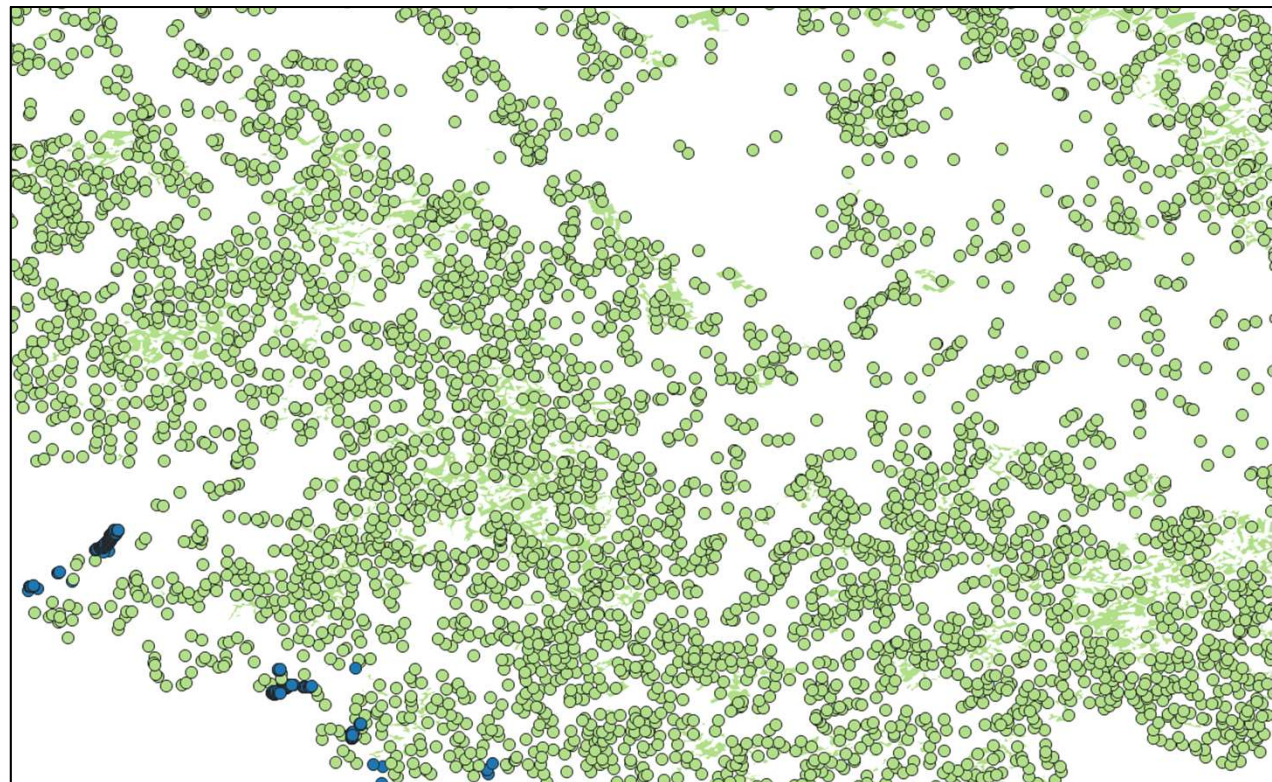
Workflow Detail: Sample Construction



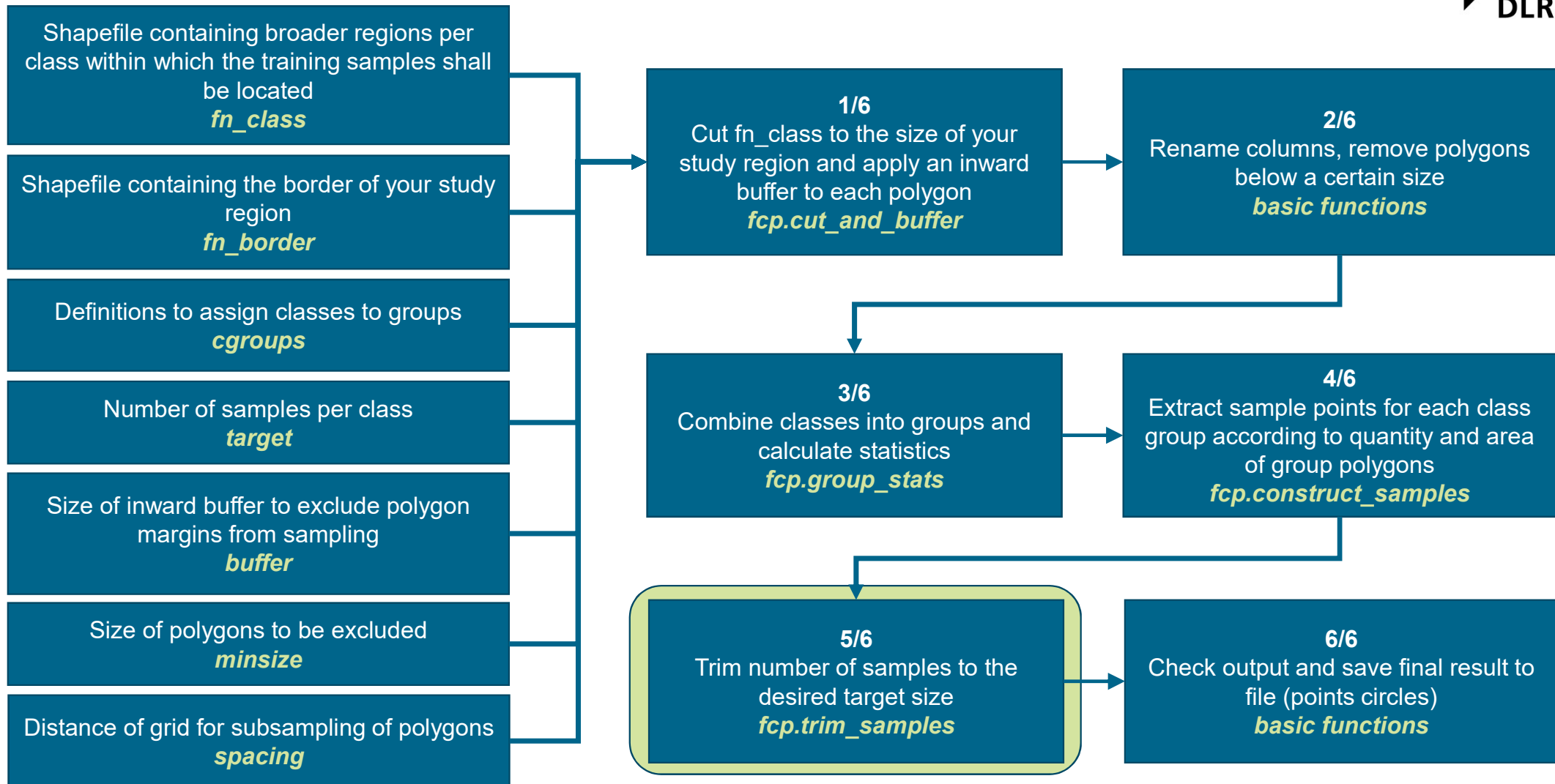
Step 4/6) Sample Construction: Center of Polygon



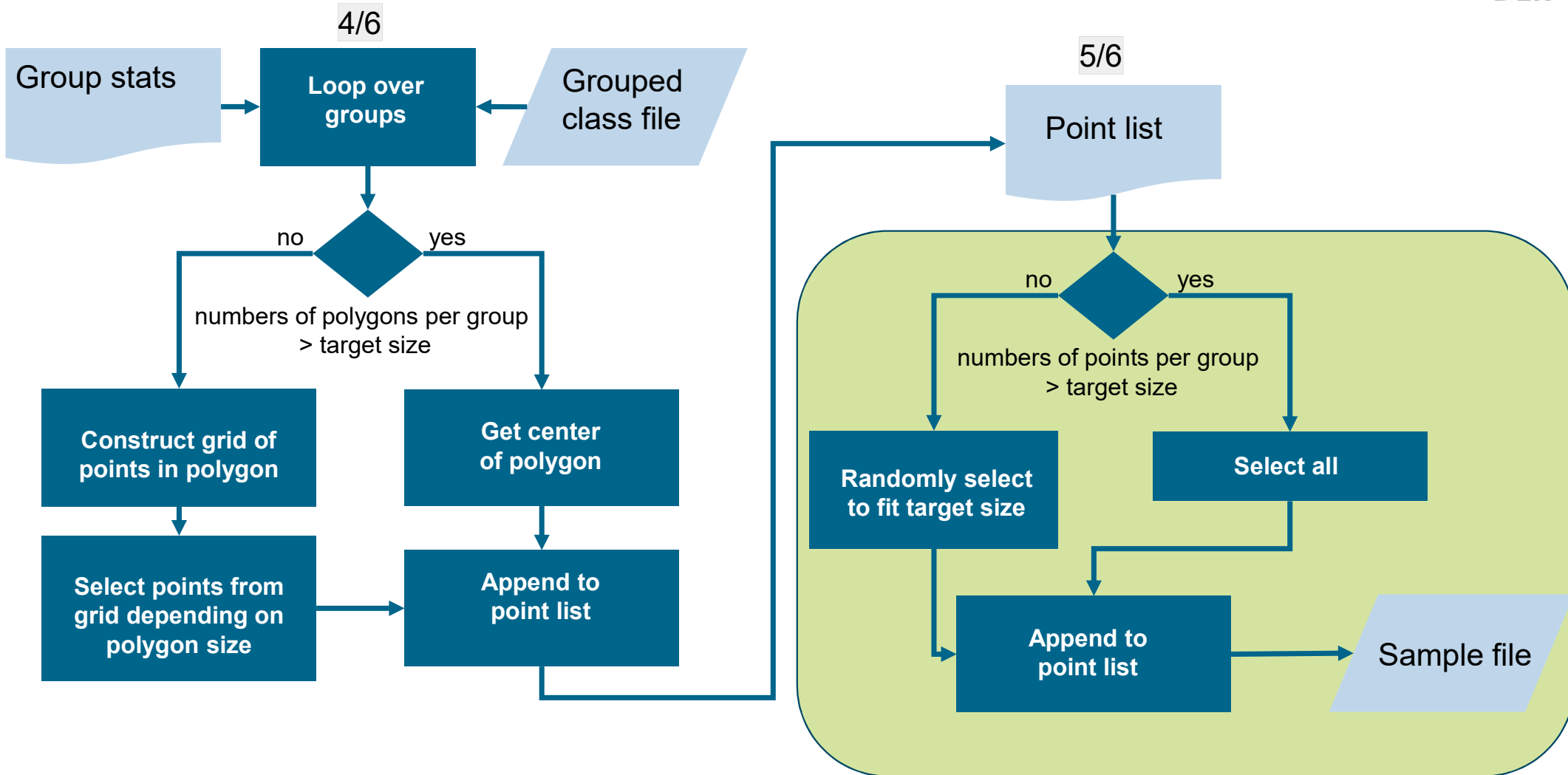
Sample Center of every polygon



Sampling Tool: General Workflow



Workflow Detail: Sample Selection

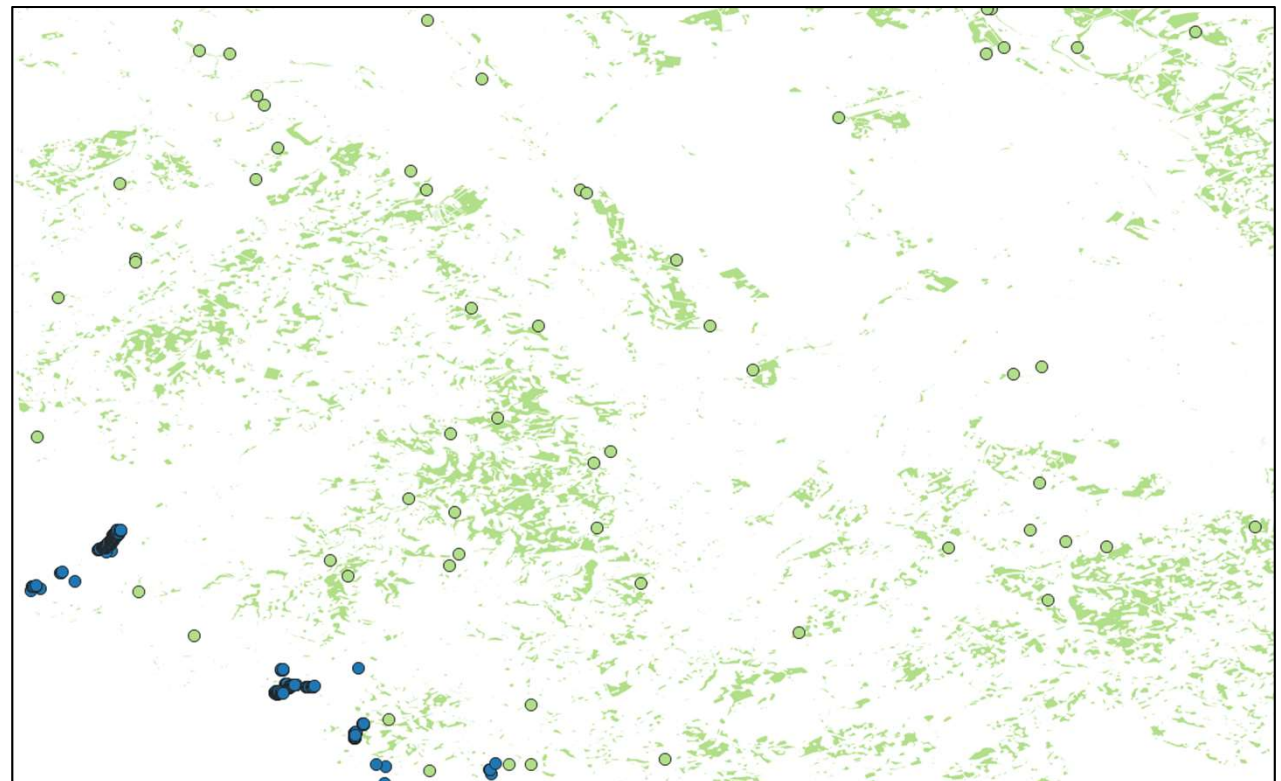


Sampling Visualization: Step 5/6) Sample Selection: Trim to Target Size

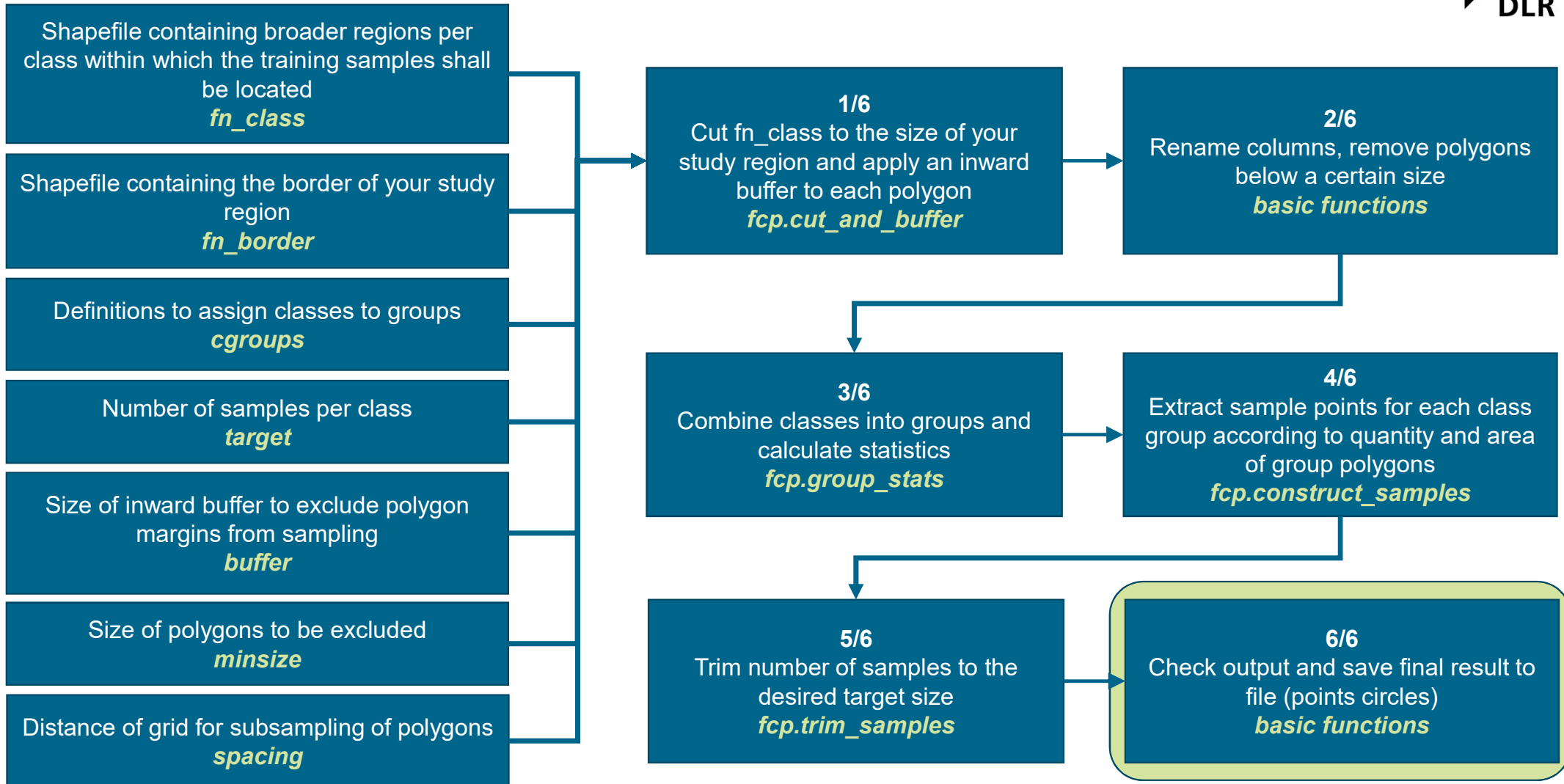


Several cases

- Too many sample points (green)
- Rounding error (blue)
 - Random selection
- Too little or right number?
 - Take all (blue)



Sampling Tool: General Workflow



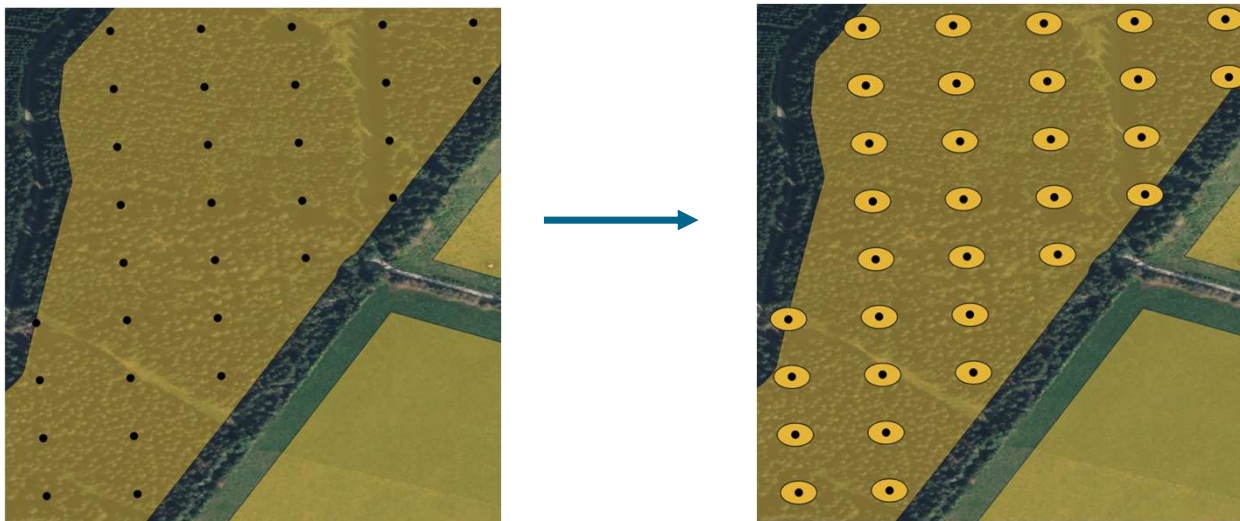
Sampling Visualization: Step 6/6) Visualize and Write Samples



Purpose

- Check numbers of sample points per group
- Quick visual control on a map
- Write sample points to file

Sampling Visualization: Bonus Step) Buffer Points



Demonstration



Stage 2

- Case: Eco System Classification: Deciduous – Coniferous Forest
- `fpcup_sampling.ipynb`

Sampling Visualization: Final Remarks



Feedback

- What is missing (data and functions)
- Different sampling strategy (stratified or not)
- Offer for short term support

Dissemination

What:

- Notebooks
- Documentation
- Training Data for all three examples

When:

- End of week after incorporation of feedback

Impressum



Thema: **FPCUP Workshop**
Concept and Live Demo

Datum: 23.11.2022

Autor: Andreas Hirner, Ursula Gessner

Institut: DFD: Land Surface Dynamics: Agricultural and Forest
Ecosystems

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